Learning To Sample: an Active Learning Framework

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Introduction: Active Learning

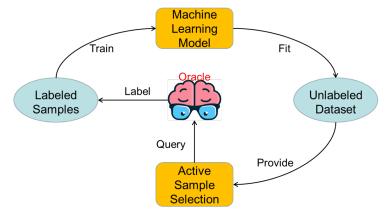


• Active learning seeks for the most representative and informative samples to be labeled by leveraging observations from previously labeled samples.

Introduction: Active Learning



- Active learning seeks for the most representative and informative samples to be labeled by leveraging observations from previously labeled samples.
- A general active learning process:





Limitation

No one-fit-all solution for active learning, i.e., the "best" varies due to the variety of datasets and machine learning models.



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Solution

Instead of using pre-defined strategies for active learning, we consider to learn the "best" active learning strategy based on the estimated performance of a model.



• Active Learning by Learning (ALBL) relates active learning with multi-armed bandit learner.

Active learning by learning, Hsu and Lin, AAAI 2015

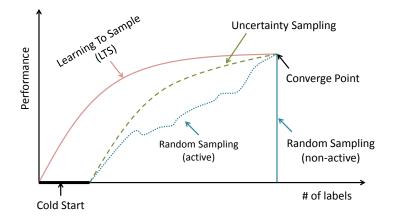
• Learning Active Learning (LAL) aims to train a regressor which can predict the generalization error reduction of each unlabelled instance and greedily select one with highest error reduction for labelling.

Learning active learning from data, Konyushkova et al., NIPS 2017

Our Objective



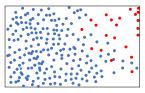
• To build a learning-based active learning framework:



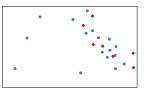
Uncertainty and Diversity



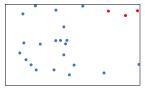
- Uncertainty sampling: using a function to measure uncertainty, e.g., probabilistic confidence, fisher information and entropy
- Diversity sampling: considering data distribution (e.g., samples with different feature values).



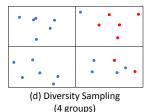
(a) Entire Data Distribution



(c) Uncertainty Sampling

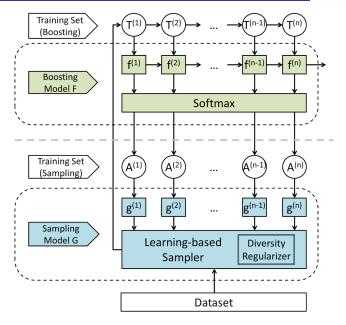


(b) Random Sampling



Learning to Sample (LTS)







• Two key components: a boosting model *F* and a sampling model *G*, dynamically learn from each other in iterations for improving the performance of each other.



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- The sampling model G incorporates uncertainty and diversity of samples into a unified process for optimization.
- We actively select samples based on the joint impacts of probabilities of being mis-classified by a boosting model and the distribution of samples in a sample space.



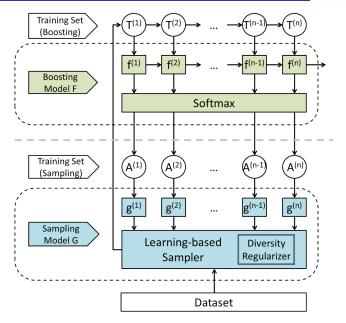
Given a training set T^(t), f^(t) ∈ F in the t-th iteration is trained by minimizing:

$$\sum_{(x_i, y_i) \in \mathcal{T}^{(t)}} \ell_1(\hat{y}_i^{(t-1)} + f^{(t)}(x_i), y_i) + \Omega_1(f^{(t)})$$

- $\begin{aligned} \hat{y}_{i}^{(t-1)} &= \sum_{k=1}^{t-1} f^{(k)}(x_{i}) \text{ is the prediction of } x_{i} \text{ in the } (t-1)\text{-th iteration;} \\ \ell_{1} \text{ is a differentiable loss function;} \\ \Omega_{1}(f^{(t)}) \text{ is the penalty for the complexity of } f^{(t)}. \end{aligned}$
- F is a sequence of functions $\langle f^{(1)}, \ldots, f^{(n)} \rangle$.

Learning based Framework (LTS)







Sampling Model G

 A sampling model G actively selects a set Δ^(t) of representative samples at the t-th iteration by:

maximize
$$\sum_{i=1}^{k} v_i g^{(t)}(x_i) + \alpha \times \Gamma(\mathbf{v})$$

subject to $||\mathbf{v}||_1 = |\Delta^{(t)}|$

where $k = |X_U^{(t)}|$, $\mathbf{v} = (v_1, ..., v_k)^T \in \{0, 1\}^k$ and α is a parameter.

- Two kinds of sampling strategies:
 - g^(t)(x_i) as a regressor, learns the uncertainty of samples which are likely to be mis-classified by the boosting model;
 - $\Gamma(\mathbf{v})$ as a regularizer, controls the diversity of samples in terms of distribution.

Strategy: Uncertainty Sampling



• Given a training set $A^{(t)}$, the regressor for uncertainty sampling is trained by minimizing:

$$\sum_{(x_i, z_i^{(t)}) \in A^{(t)}} w_i^{(t)} \ell_2(g^{(t)}(x_i), z_i^{(t)}) + \Omega_2(g^{(t)})$$

where:

- $A^{(t)} = \{ (x_i, z_i^{(t)}) | (x_i, y_i) \in T^{(t)}, z_i^{(t)} \in [0, 1] \};$
- $z_i^{(t)}$ represents the uncertainty of a sample x_i in $T^{(t)}$;
- $w_i^{(t)}$ is a weight for x_i ;
- ℓ_2 is a differentiable loss function;
- $\Omega_2(g^{(t)})$ is the penalty for the complexity of $g^{(t)}$.



Given a number of partitioned groups {ν₁,..., ν_b} from the sample space ν, the diversity Γ(ν) is defined using a I_{2,1}-norm function:

$$\Gamma(\mathbf{v}) = ||\mathbf{v}||_{2,1} = \sum_{j=1}^{b} ||\mathbf{v}_j||_2$$

where:

$$\begin{array}{l} - \ \Sigma_{j=1}^{b} |\mathbf{v}_{j}| = |\mathbf{v}|; \\ - \ \mathbf{v}_{j} \in \{0, 1\}^{m}; \\ - \ m = |X_{j}^{(t)}|. \end{array}$$



Datasets	# of			Class Imbalance				
Datasets	Attributes	Instances	nstances Classes I					
Image classification								
Mnist	28×28	60,000	10	N/A				
Salary level prediction								
Adult	14	48,842	2	1:3				
Entity resolution								
Cora	12	837,865	2	1:49				
DBLP-Scholar	4	168,112,008	2	1 : 71,233				
DBLP-ACM	4	6,001,104	2	1:2,698				
NCVoter	18	10M	2	1:420				



- CART: Classification And Regression Tree
- XG: eXtreme Gradient Boosting
 - + RS: Random sampling
 - + US: Uncertainty sampling
 - + DS: Diversity sampling
 - + LTS: Learning to sample with equal sampling distribution
 - + LTS(E): Learning to sample with exponentially decreasing sample budget

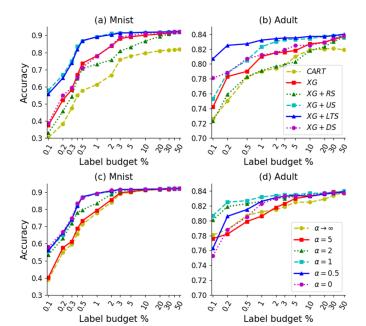
Results: Different Label Budgets



Deterret	Label Budget ζ	CART	XG	XG+RS	XG + US	XG+LTS	XG + DS	XG + LTS(E)
Dataset (% of X)	(% of X)	CART	٨G	XG+KS	$\alpha = 0$	$\alpha = 1$	$\alpha \to \infty$	$\alpha = 1$
	0.01	0	0	0	0	0.857	0.878	0.862
Cora	0.05	0.741	0.763	0.750	0.827	0.864	0.885	0.867
	0.1	0.788	0.796	0.787	0.823	0.862	0.886	0.870
	0.5	0.848	0.835	0.835	0.873	0.900	0.893	0.890
	1	0.868	0.878	0.880	0.870	0.902	0.894	0.896
	5	0.878	0.897	0.892	0.907	0.915	0.898	0.904
	0.01	0	0	0	0	0.324	0.875	0.571
	0.05	0	0	0	0	0.954	0.991	0.934
NCVoter	0.1	0	0	0	0	0.994	0.993	0.993
NCvoter	0.5	0	0	0	0	0.994	0.991	0.994
	1	0.334	0.379	0.398	0	0.993	0.994	0.993
	5	0.993	0.993	0.994	0.993	0.997	0.993	0.994
	0.1	0	0	0	0	0	0.397	0
	0.5	0	0	0	0	0.702	0.632	0.679
DBLP- ACM	1	0.348	0.347	0.279	0	0.878	0.721	0.793
	2	0.599	0.767	0.680	0.403	0.884	0.783	0.854
	5	0.870	0.850	0.803	0.874	0.931	0.833	0.891
	10	0.903	0.911	0.890	0.926	0.981	0.899	0.933
	0.1	0	0	0	0	0.723	0.731	0.727
	0.5	0.378	0.54	0.498	0.555	0.773	0.780	0.781
DBLP-	1	0.562	0.669	0.659	0.738	0.804	0.792	0.794
Scholar	2	0.772	0.806	0.771	0.807	0.815	0.801	0.811
	5	0.773	0.822	0.803	0.836	0.836	0.818	0.828
	10	0.808	0.835	0.830	0.865	0.851	0.829	0.853

Results: Different Label Budgets





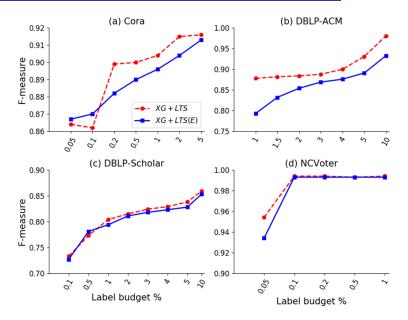
Results: Different α



Dataset	Label Budget ζ	XG + US	XG+LTS			XG + DS	
Dataset	(% of X)	$\alpha = 0$	$\alpha = 0.5$	$\alpha = 1$	$\alpha = 2$	$\alpha = 5$	$\alpha \to \infty$
Cora	0.01	0	0.637	0.857	0.861	0.867	0.878
	0.05	0.827	0.851	0.864	0.870	0.883	0.885
	0.1	0.823	0.863	0.862	0.873	0.887	0.886
	0.5	0.873	0.893	0.900	0.895	0.895	0.893
	1	0.870	0.896	0.902	0.904	0.898	0.894
	5	0.907	0.912	0.915	0.913	0.902	0.898
	0.01	0	0.403	0.324	0.403	0.752	0.875
NCVoter	0.05	0	0.903	0.954	0.989	0.993	0.991
	0.1	0	0.989	0.994	0.993	0.993	0.993
NCVoter	0.5	0	0.993	0.994	0.993	0.993	0.991
	1	0	0.993	0.993	0.993	0.992	0.994
	5	0.993	0.993	0.997	0.993	0.994	0.993
DBLP- ACM	0.1	0	0	0	0	0	0.397
	0.5	0	0.382	0.702	0.720	0.651	0.632
	1	0	0.813	0.878	0.778	0.730	0.721
	2	0.403	0.851	0.884	0.867	0.789	0.783
	5	0.874	0.935	0.931	0.889	0.837	0.833
	10	0.926	0.983	0.981	0.937	0.893	0.899
	0.1	0	0.586	0.723	0.733	0.741	0.731
	0.5	0.555	0.764	0.773	0.794	0.790	0.780
DBLP-	1	0.738	0.793	0.804	0.808	0.793	0.792
Scholar	2	0.807	0.810	0.815	0.813	0.799	0.801
	5	0.836	0.838	0.836	0.831	0.821	0.818
	10	0.865	0.859	0.851	0.844	0.837	0.829

Results: Sampling Distribution







• Comparison of label budgets w.r.t. classification results with a desired FM value, where XG+LTS has $\alpha = 1$.

Dataset	Cora	DBLP-ACM	DBLP-Scholar	NCVoter
CART	5%	10%	10%	3%
XG	4%	8%	2%	2%
XG + RS	5%	12%	5%	2%
XG + US	2%	7%	2%	7%
XG + DS	3%	10%	2%	0.03%
XG + LTS	0.5%	4%	0.9%	0.03%
FM values	0.9	0.9	0.8	0.9



- We propose a novel active learning framework, namely Learning To Sample (LTS).
- Our sampling model incorporates uncertainty and diversity of samples into a unified process for optimization.
- The experimental results show that our active learning approach significantly outperforms all the baselines when the label budget is limited.

Thank You!

Q & A

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